

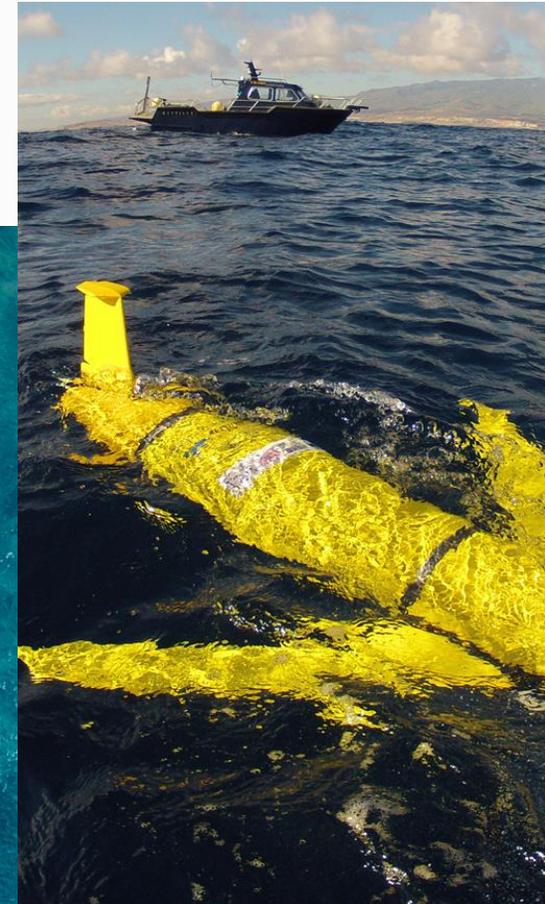


National
Oceanography
Centre

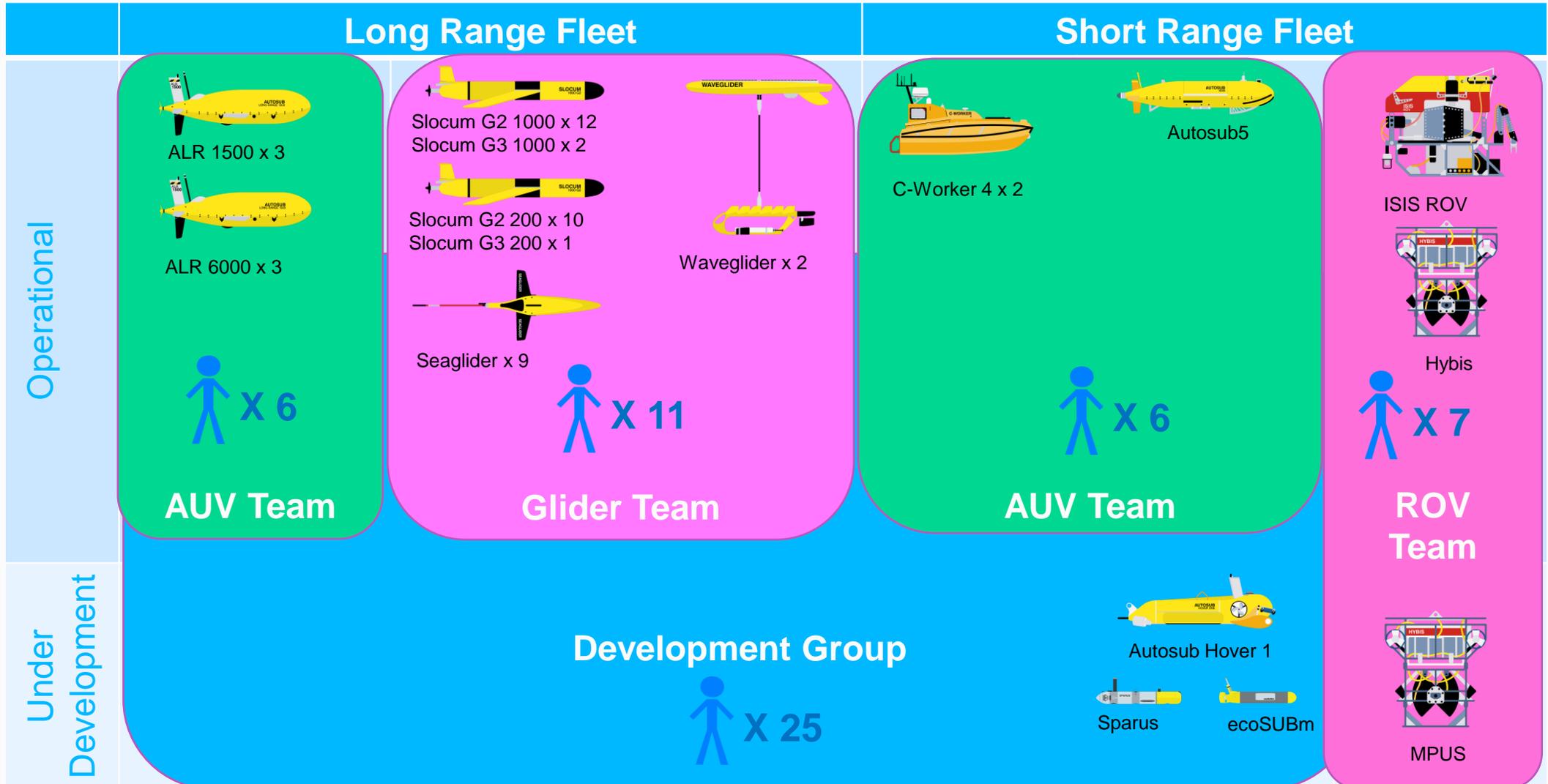
**OVER THE HORIZON AND
UNDER ICE ADVANCES IN
MARINE ROBOTICS FROM
NOC**

14-06-2024

MAATEN FURLONG



NMF MARINE ROBOTICS AND AUTONOMOUS SYSTEMS (MARS) TEAMS



3 x Autosub Long Range
6000 (ALR6000)

- 2 x Pressure Vessel
- 38kWhrs Primary LTC Batteries
- 6000m depth rating
- Mass \approx 800 kg
- Length \approx 3.5m
- Top Speed \approx 1m/s
- Max Range \approx 2000km

- 1 x Pressure vessel
- 95kWhrs Primary LTC batteries
- 1500m depth rated
- Mass \approx 800 kg
- Length \approx 3.5m
- Top Speed \approx 1m/s
- Max Range \approx 6000km

3 x Autosub Long
Range1500 (ALR1500)

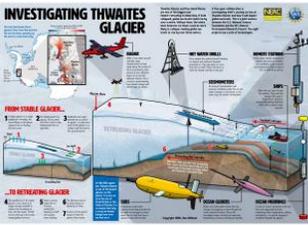
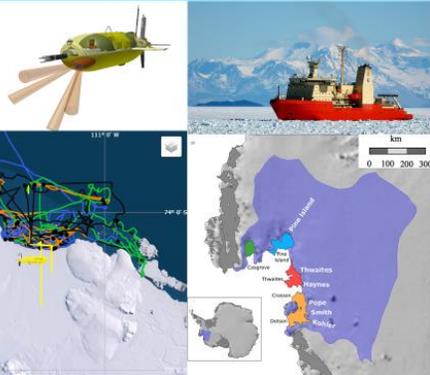


RECENT ALR MISSIONS

TARSAN – Q1 '22



Multi-day deployment of ALR1 from the Nathaniel B Palmer under Dotson Glacier as part of TARSAN International Thwaites Glacier Collaboration
 Longest track was 40km in under the ice flying at circa 100m altitude

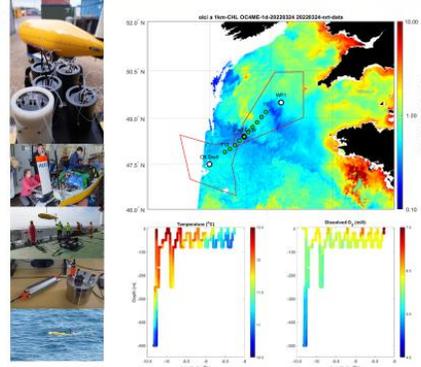


<https://thwaitesglacier.org/projects/tarsan>

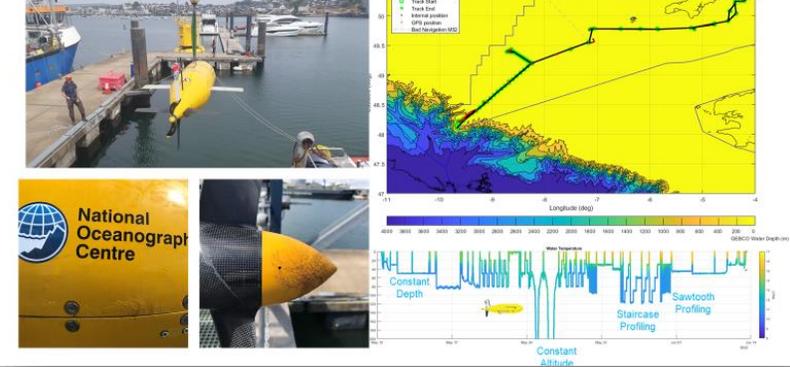
BIOGEOCHEMISTRY (DY149) – Q1 '22



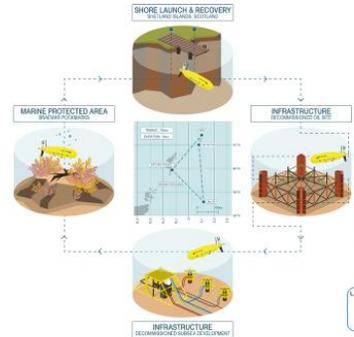
AUV	ALR2
Depth Rating	8000 m (Nominal) Currently de-rated to 600 m for sensor payload
Energy	Lithium Thiocyl Chloride (~10 Days)
System sensors	<ul style="list-style-type: none"> 300 kHz RDI ADCP PNI Magnetic Heading Sensor CTD SBE 52 ADCP's as per system ADCP's DO SBE 43F
Science sensors	<ul style="list-style-type: none"> AutoNuts – Nutrients <ul style="list-style-type: none"> LOC Nitrate LOC Silicate LOC Iron (Chemiluminescent) LOC Iron LOC Nitrite LOC Phosphate Carcass – Carbonate <ul style="list-style-type: none"> LOC pH LOC TA LOC DIC ANB pH Stafes-App – Primary Productivity



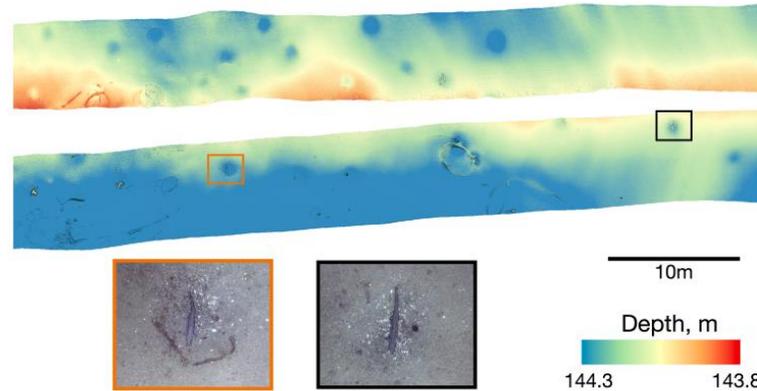
LONG DISTANCE PROVING TRIAL (LDPT) APRIL 22



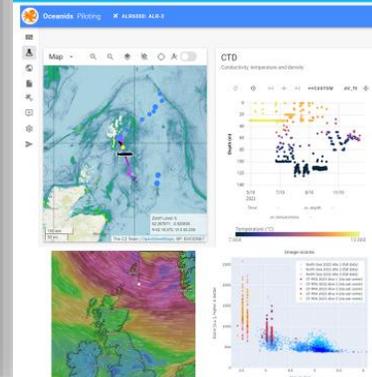
INSITE ATSEA (SEPT/OCT 2022)



- INSITE is an independent science programme examining the effects of man-made structures in the North Sea
- The Autonomous Techniques for anthropogenic Structure Ecological Assessment ATSEA project is aiming to assess the feasibility and efficacy of fully autonomous monitoring of multiple decommissioning-related sites without the aid of a support vessel by demonstrating the use of an existing shore-launched, long-range, fully autonomous underwater vehicle for marine environmental survey.



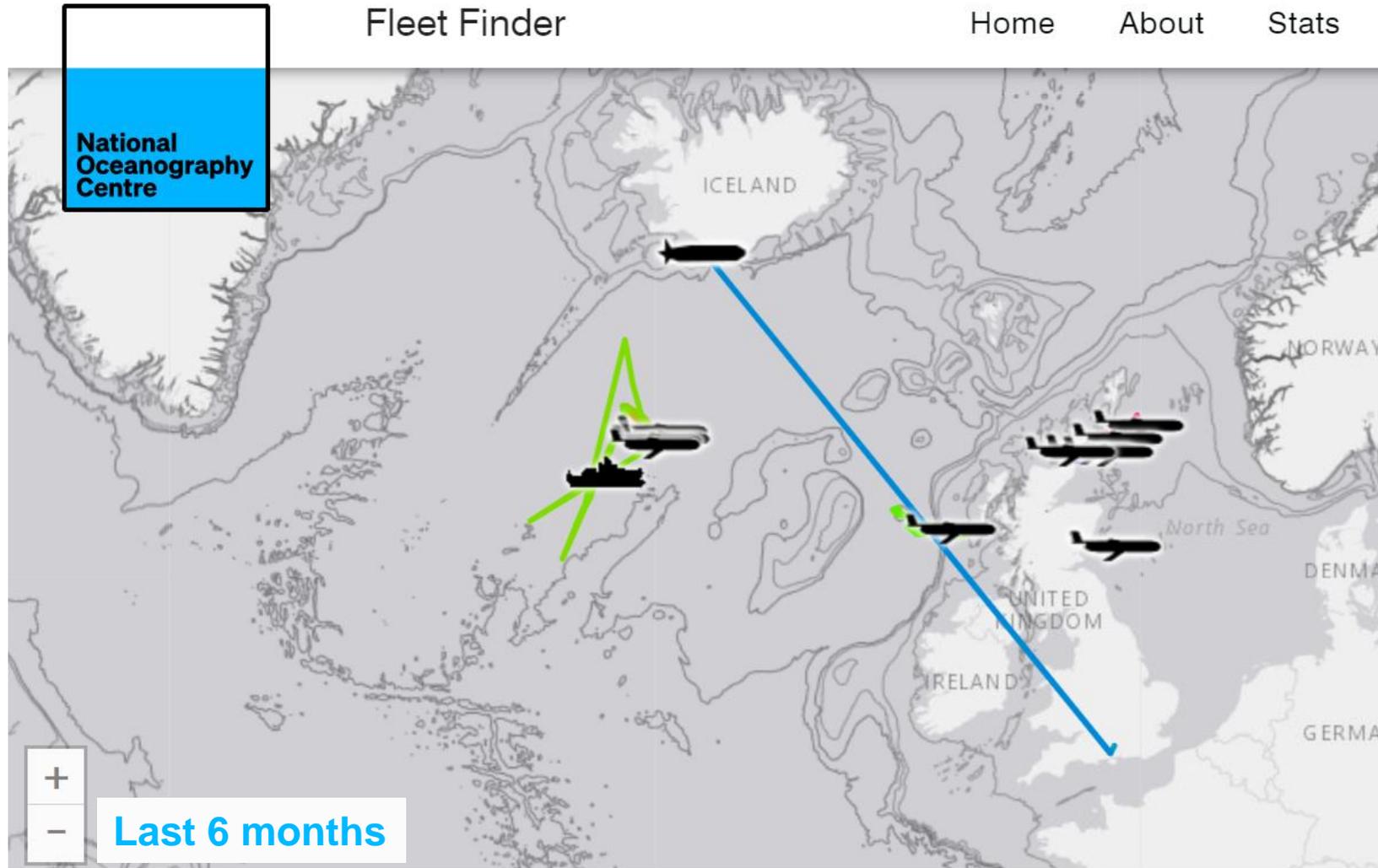
OCTOBER 2023 CENTRAL FLADDON MPA SURVEY



- ALR4 was deployed from Lerwick on the 4th October, following a short tow the AUV traversed 110 km to the Central Fladdon MPA.
- Within the MPA the system took ~1M images with the BioCAM imaging system flying between 3.5m and 4.5m altitude from the seabed.
- Having completed the survey the AUV transited back to Lerwick. Recovery was delayed by strong Autumn gales which the AUV waited out loitering subsea.



WHAT IS HAPPENING NOW (ISH)



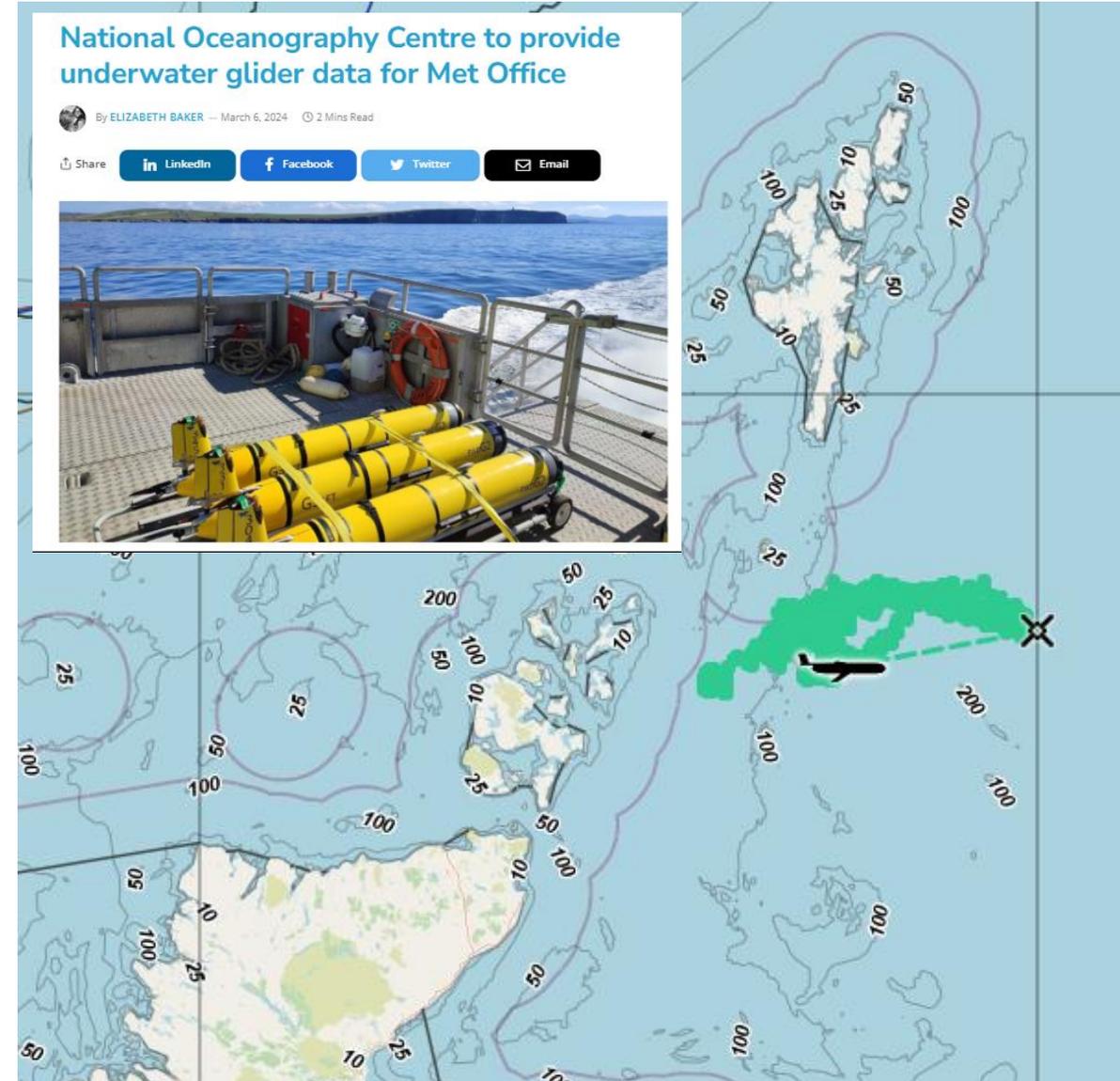
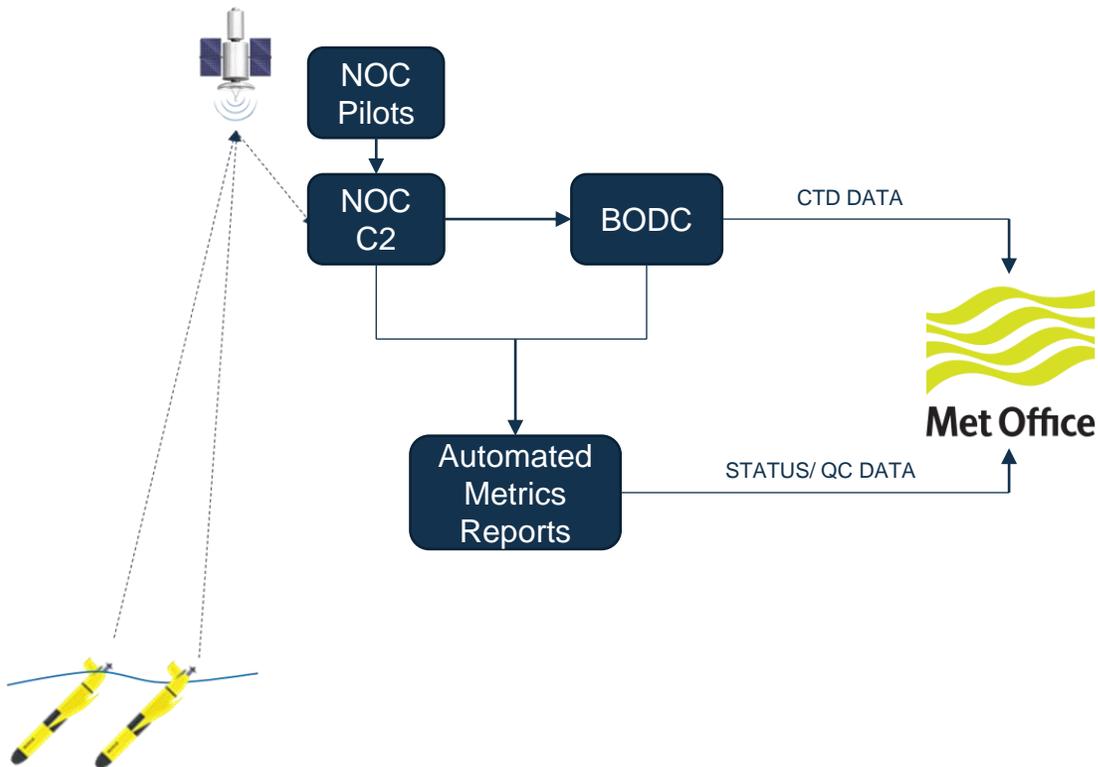
Last year of operations



MOGLI - UK MET OFFICE GLIDER PROJECT CONTINUOUS PRESENCE ON THE JONSIS LINE

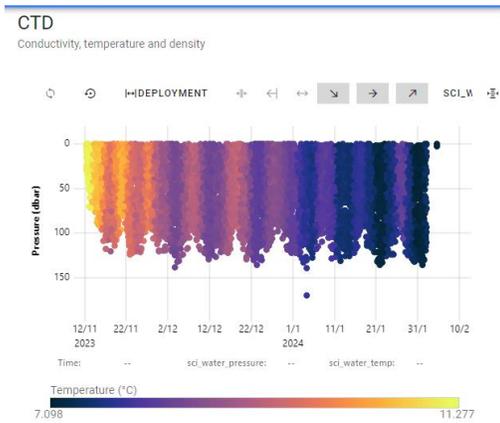


- Patrolling Western end of the JONSIS Line for last 21 months
- Providing Near Real Time Conductivity, Temperature, & Depth (CTD) Data that is fed into the AMM 15 ocean model.



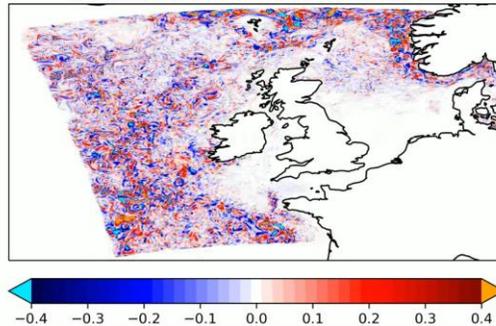
MOGLI – THE GOOD AND THE BAD

The Good – positive impact on model performance



AMM15 Results – surface temperature field difference over time

experiment-control 20221028 model run: -36



The Bad – We lost a glider



We had factored a loss into the project

BIPOLE (DEC 23-FEB 24)



Natural Environment Research Council

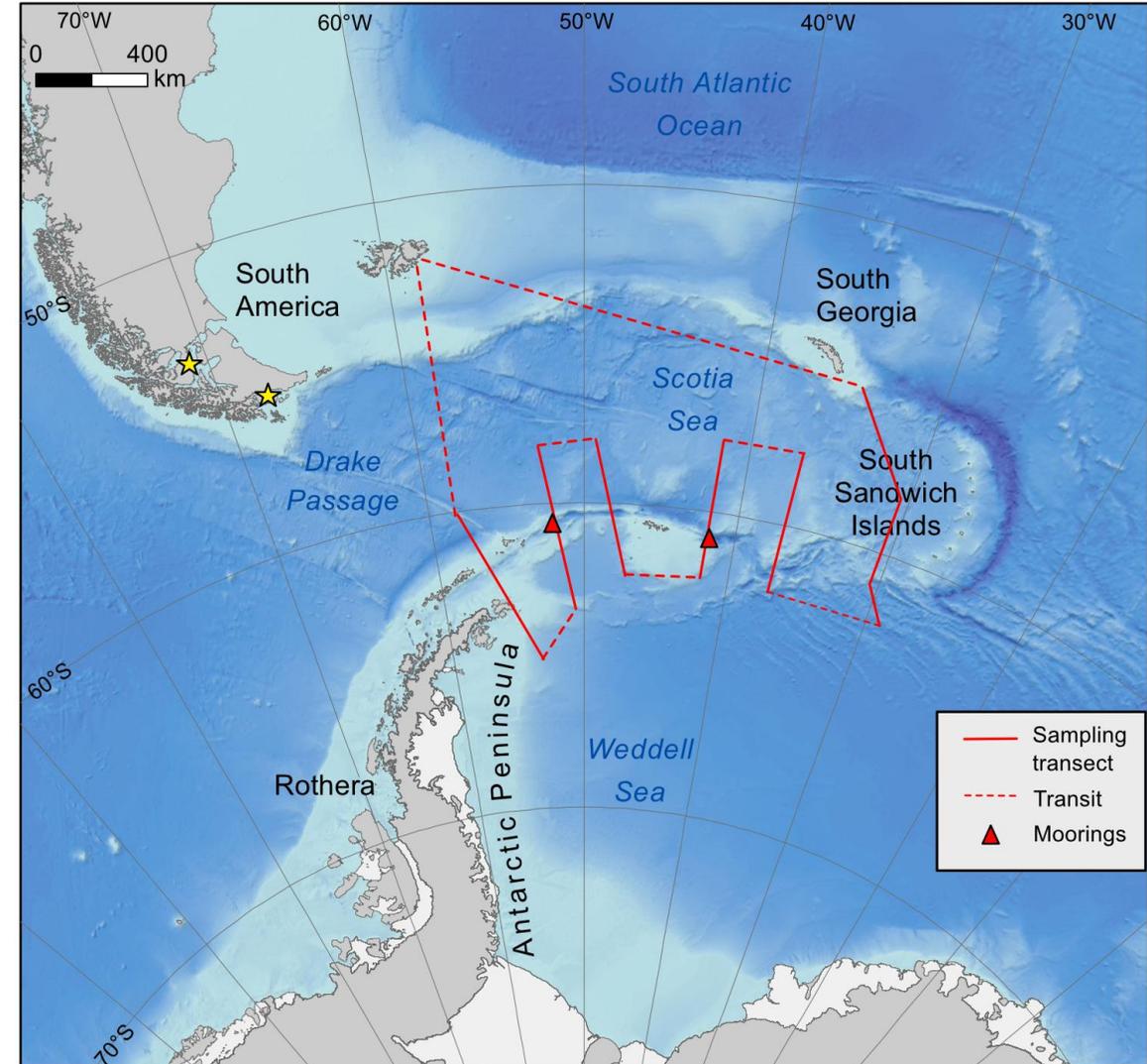


British Antarctic Survey

NATURAL ENVIRONMENT RESEARCH COUNCIL



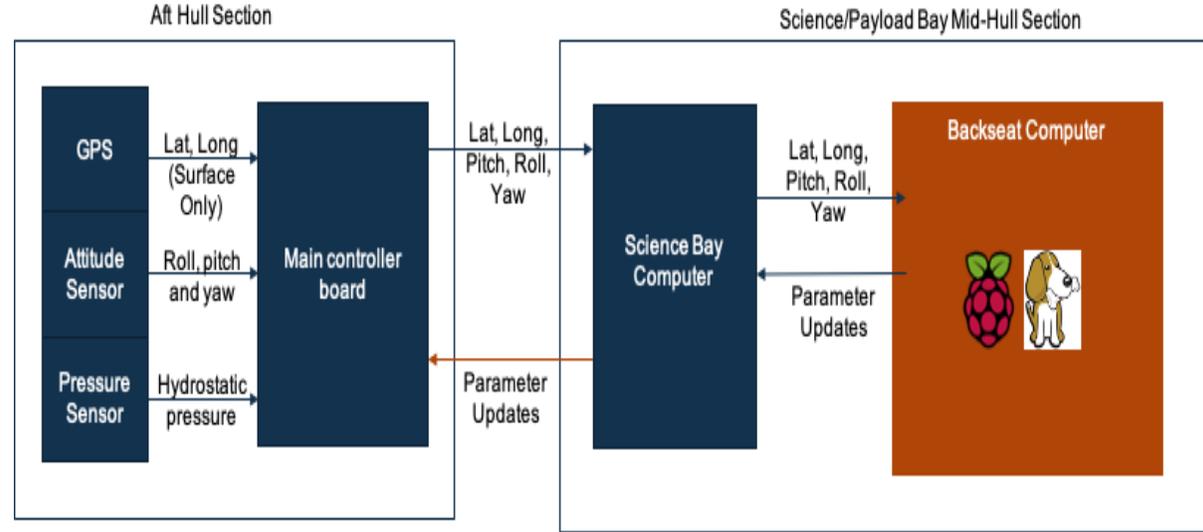
- BIPOLE is an interdisciplinary NERC programme examining biogeochemical processes and ecosystem function in polar ecosystems.
- An Observational campaign in the Weddell sea using of ships, moorings and gliders
- Gliders made short duration missions under retreating sea ice using a Backseat Driver and upwards altimeter to enable this capability



BIPOLE – GLIDER BACK SEAT DRIVER

Goal

Develop ice coping strategies and add to a “backseat driver” to control the gliders under ice

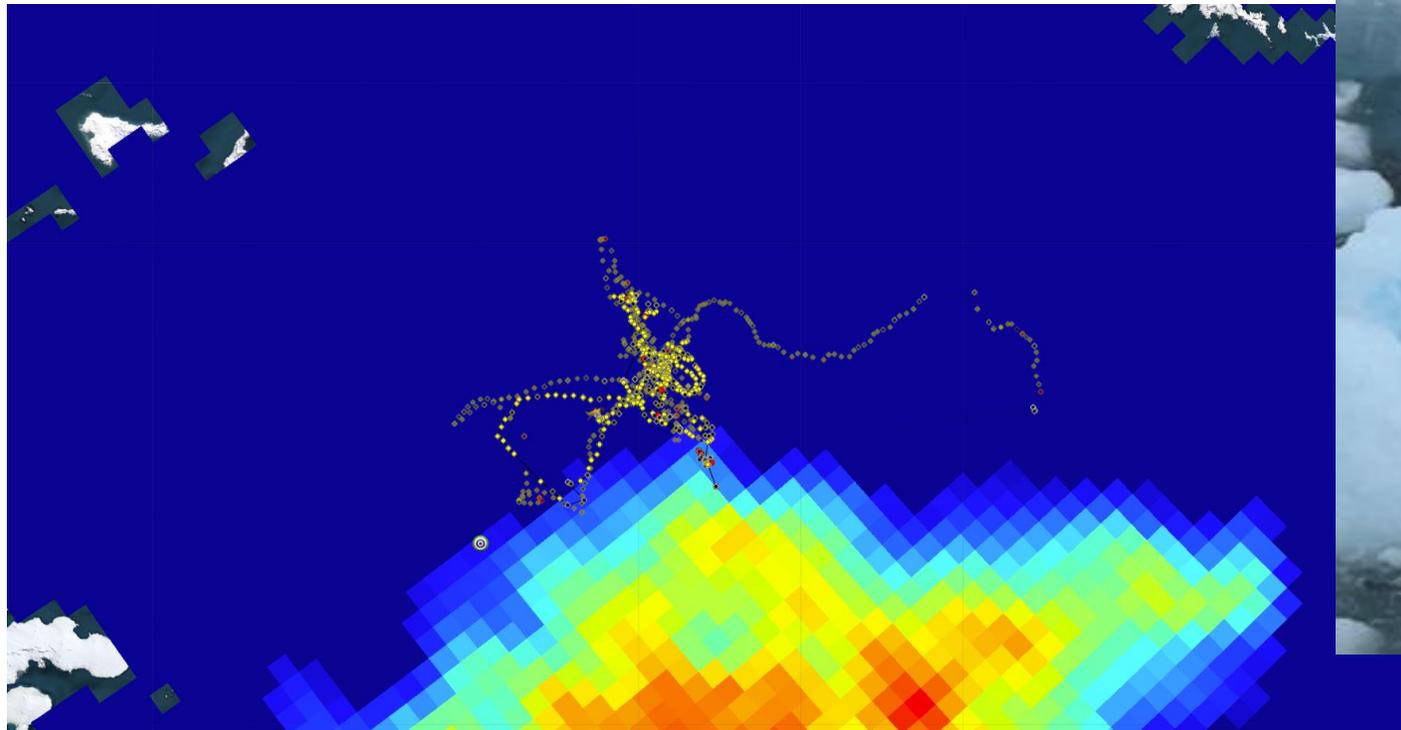


Ice sensing strategies

Median temperature	Ice draft	Ice edge
<ul style="list-style-type: none"> • Median temperature 	<ul style="list-style-type: none"> • Ice draft <p>The ice draft D_i is $D_i = D_p - D_a * \cos(\theta) \in \{(-\infty, b), \text{uncertainty}\}$ $\{ (b, +\infty), \text{ice area} \}$ D_p: CTD depth D_a: Upward-looking altitude θ: Angle of the upward-looking altimeter b: The minimum detectable ice draft</p>	<ul style="list-style-type: none"> • Ice edge <p>Boundary points location $d = f(\text{mission time, ice edge})$</p>
<p>Figure 5. Measuring the median temperature of mixed layer.</p>	<p>Figure 6. Ice draft which is the difference between CTD depth and upward-looking altitude.</p>	<p>Figure 7. Ice edge for defining the boundary points between ice area and open water area.</p>

GLIDER OPERATIONS – IT WAS VERY DIFFICULT

Piloting using satellite data to get into and out
of the marginal ice zone



Gliders just before being “munched” by the ice



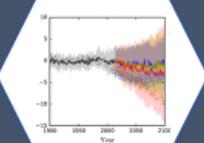
Lots of lessons to learn about the
environment and bes approach to it

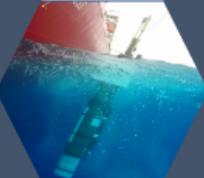
THE BIOCARBON PROGRAMME

The major science questions



 How does marine life affect the ability of seawater to absorb carbon dioxide, and how will this change?

 How will the rate at which marine life consumes carbon dioxide change?

 How long can marine life store carbon in the ocean and how will climate change affect this?

BIO-Carbon programme

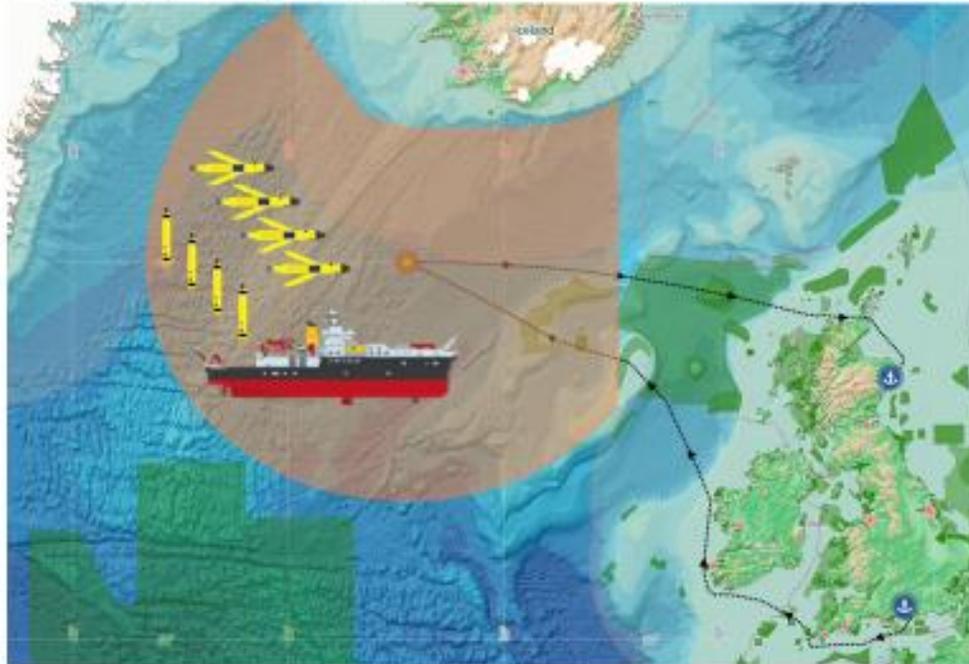


- Focussed on understanding role of marine life in ocean carbon storage and how this will alter under climate change
- Baseline information necessary for many mCDR discussions
- Strategic Programme, £10.3M, spanning ~6 years, started 2022
- Nine projects already funded, including a gap analysis (BRICS)
- Three fieldwork projects - 6 months of activity just begun
- Final stage will be aimed at modelling and synthesis

THE BIOCARBON PROGRAMME

Fieldwork

Spring cruise – DY180
21 May – 27 June



BIO-Carbon-FMRI ALR mission
June - August



BIOCARBON ALR SPECS



Natural Environment Research Council



FUTURE MARINE RESEARCH INFRASTRUCTURE



MiXed Layer ALR (ALR4)



TRIOS RAMSES hyperspectral radiometer:
ACC-VIS (320-950nm)



LoC:

2 x OTE LoC

• TA

• DIC

4 x OTE LoC

• pH

• Nitrate

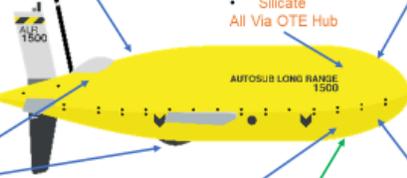
• Phosphate

• Silicate

All Via OTE Hub



eco-triplet: BBFLCD (chlorophyll, backscatter 700nm, fdom)
<https://seacatalog.com/product/wet-labs-eco-flird-fluorometer/>



AquapHOx-LX (standalone)



Nortek 500 DVL/ADCP: down current measurement
<https://www.nortekgroup.com/products/dvl500-6000-m/pdf>



CTD+DO: SBE 52MP CTD and 43F dissolved oxygen sensor.
<https://www.seabird.com/sbe-52-mp-moored-profiler-ctd-and-optional-do-sensor/product?id=60762467706>

UVP6: The Underwater Vision Profiler or UVP (CNRS patent) is designed to study large (>100 µm) particles and zooplankton simultaneously and to quantify them in a known volume of water. The UVP system makes use of computerised optical technology with custom lighting to acquire digital images of zooplankton IN SITU down to depths of 6000m.
http://www.hydroptic.com/index.php/public/Page/product_item/UVP6-LP

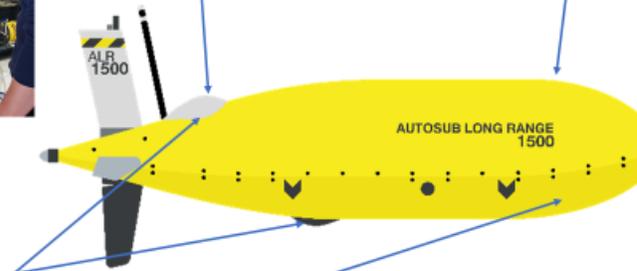
Profiling ALR (ALR6)



TRIOS RAMSES hyperspectral radiometer:
ACC-VIS (320-950nm)



eco-triplet: BB2FL (with chlorophyll, backscatter 532nm and 70nm)
<https://seacatalog.com/product/wet-labs-eco-flird-fluorometer/>



MicroRider:
Turbulence Probe.
<https://rocklandscientific.com/products/modular-systems/microrider/>



Nortek 500 DVL/ADCP: down current measurement
<https://www.nortekgroup.com/products/dvl500-6000-m/pdf>



CTD+DO: SBE 52MP CTD and 43F dissolved oxygen sensor.
<https://www.seabird.com/sbe-52-mp-moored-profiler-ctd-and-optional-do-sensor/product?id=60762467706>



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http://www.hydroptic.com/index.php/public/Page/product_item/UVP6-LP

WHAT'S HAPPENING NOW?



Natural Environment Research Council



FUTURE MARINE RESEARCH INFRASTRUCTURE

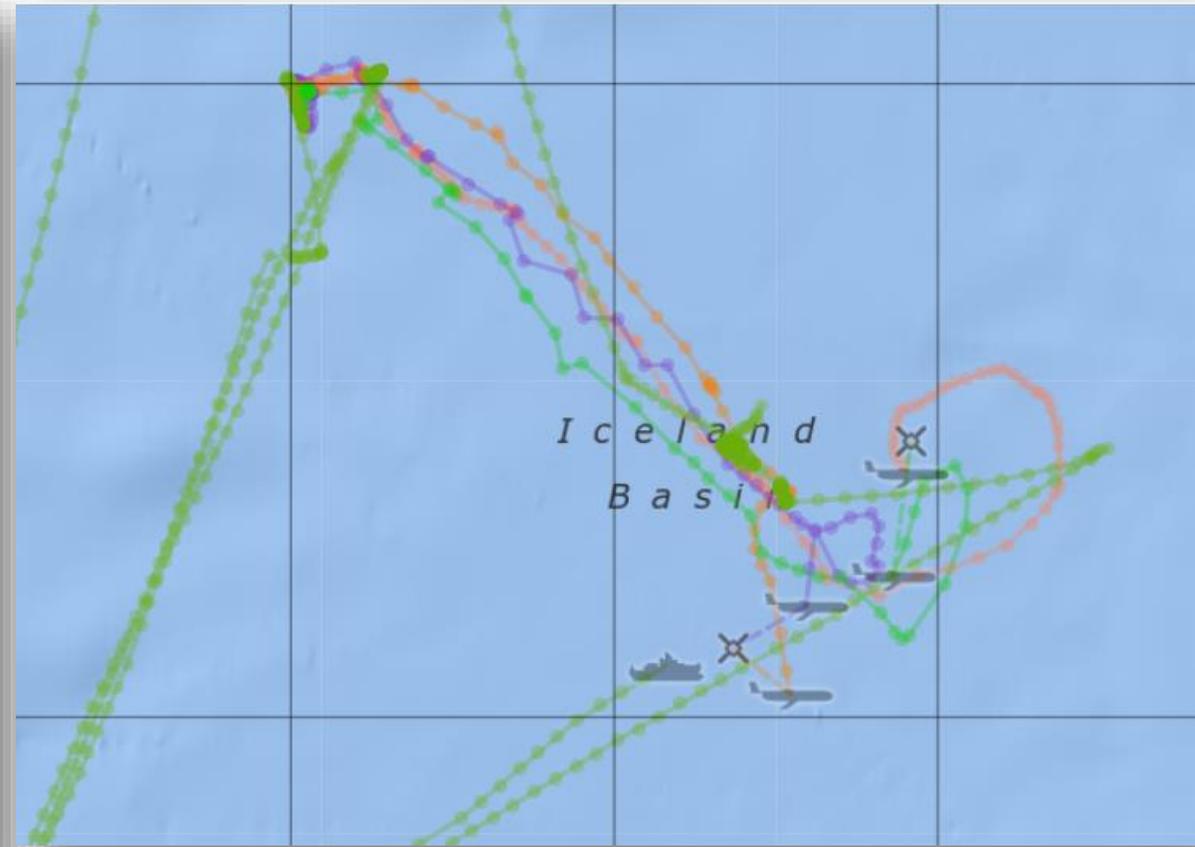


Oceanids Piloting ✈ SELECT PLATFORM

Platforms < Map +

Search Platforms

- rrs-discovery**
No connection history
Status: unknown
- alr-6**
26 minutes ago
Status: ready
- alr-4**
2 hours ago
Status: ready
- unit_405**
in 19 seconds
Status: pitch not comma...
- unit_398**
3 hours ago
Status: pitch not comma...
- unit_397**
3.5 hours ago
Status: pitch not comma...
- unit_345**
2 hours ago
Status: pitch not comma...



Follow progress on:
<https://bio-carbon.ac.uk>
<https://mars.noc.ac.uk/>

FINAL THOUGHTS – AND LESSONS LEARNED

- Marine Robotics are just other tools in the toolbox they don't replace ships but augment them
- You will lose them at some points
- To get the best out of marine robotics you need to have:
 - Staff with a deep understanding of the tech
 - Detailed knowledge of the environment you are operating in
 - Good processes and tools to support the staff
 - Luck is also always useful
- Combined ship operations and autonomy provide interesting opportunities

